

conditions it may look to determine causal and/or flow agents and further project and/or learn based on such inferences.

[2434] An artifact may comprise an intrinsic, variable likeable and/or resonant orientation (e.g. a car is oriented from backward facing to forward facing, a building is oriented from the back façade to the main façade etc.). The system may determine facings based on inferences and/or further leadership artifacts on forward/backward mapped endpoints and/or observing views from/to such endpoints. In some examples, the system determines the forward facing of a car by the leadership presence of headlights and/or the lack of rear lights and, by WENT, the backward facing by the absent (NO) headlights and/or presence of the rear lights. It is to be understood that the (leadership) resonant components may be based on resonance, grouping and/or entanglement with users, manufacturers, owners, supervisors, visitors and/or other (targeted) (leadership) semantic identities.

[2435] The system identifies the orientation of an artifact by determining its positioning, activities and/or further observing views (e.g. the artifact is oriented towards the more affirmative resonant observing views and/or endpoints, the artifact is oriented so its (affirmative resonant) leadership artifacts are accessible, visible and/or more affirmative with its use, users and/or activities.

[2436] The various examples presented in the application may be substituted, expanded and/or analyzed according with techniques explained in the application. As such, the examples and/or their further semantics may be substituted for any other examples and/or semantics which may be inferred based on such techniques.

[2437] It is to be understood that the term “system” used in this disclosure may take various embodiments based on the contexts as disclosed. In some examples, “system” may represent, but not limited to, a post, a semantic cloud, a composable system, a semantic engine, a semantic networked system, a semantic memory, a semantic unit, chip, modulator, controller, mesh, sensor, I/O device, display, actuator, electronic block, component, semantic computer, mobile device, robotic device, sound device, ultrasound device, optical device, generator, appliance, point of sale, wearable and any combination thereof.

[2438] Further, any functionality implemented in hardware may be implemented in software and vice-versa. Also, functionalities implemented in hardware may be implemented by a variety of hardware components, devices, computers, networks, clouds and configurations.

[2439] While the preferred embodiment of the invention has been illustrated and described, as noted above, many changes can be made without departing from the spirit and scope of the invention. Accordingly, the scope of the invention is not limited by the disclosure of the preferred embodiment. Instead, the invention should be determined entirely by reference to the claims that follow.

I claim:

1. A flux sensing system, comprising:
a processor and a memory associated with the flux sensing system,
a sensor communicatively coupled to the processor,

the memory storing a plurality of endpoints mapped to physical locations, and a plurality of capabilities,

the memory further storing at least two semantic fluxes, each one of the at least two semantic fluxes being associated with at least one of the plurality of capabilities,

wherein the memory contains programming instructions configured to cause the processor to infer a semantic associated with an item at one of the plurality of endpoints, the inferred semantic being based on an input from the sensor, and

wherein further the flux sensing system orients a flow agent towards the item to route the item to at least one of the at least two semantic fluxes based on a semantic drift inference between published capabilities of the at least two semantic fluxes and the inferred semantic.

2. The flux sensing system of claim 1, wherein the sensor is positioned in a device orienting and routing the flow agent.

3. The flux sensing system of claim 2, wherein the sensor is external to the device.

4. The flux sensing system of claim 1, wherein the system projects a composite flow agent by bonding the item to the flow agent and further orients the flow agent to encompass the item and form the composite flow agent.

5. The flux system of claim 1, wherein the item is identified as a debris of an interest article.

6. The flux system of claim 1, wherein the item is identified as a by-product of an interest article.

7. A flux sensing system, comprising:

a processor and a memory associated with the flux sensing system,

the memory storing a plurality of location-based endpoints and a plurality of capabilities,

the memory further storing at least two semantic fluxes associated with the plurality of capabilities,

wherein the system infers a semantic associated with an order placed by a user of a device localized at one of the endpoints,

and wherein further the system routes the data from the order to at least one of the semantic fluxes based on semantic drift inference between the capabilities at of the at least two semantic fluxes and the inferred semantic.

8. The flux sensing system of claim 7, wherein the semantic is inferred based on an input from a sensor.

9. The flux sensing system of claim 8, wherein the sensor is attached to the device.

10. The flux sensing system of claim 8, wherein the sensor is external to the device.

11. The flux sensing system of claim 8, wherein the device is further positioned by the system to accept inputs from the user in an optimized manner.

12. The flux sensing system of claim 11, where the optimized manner is based on an inference from the sensor.

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